Home, SafeHome: Smart Home Reliability with Visibility and Atomicity

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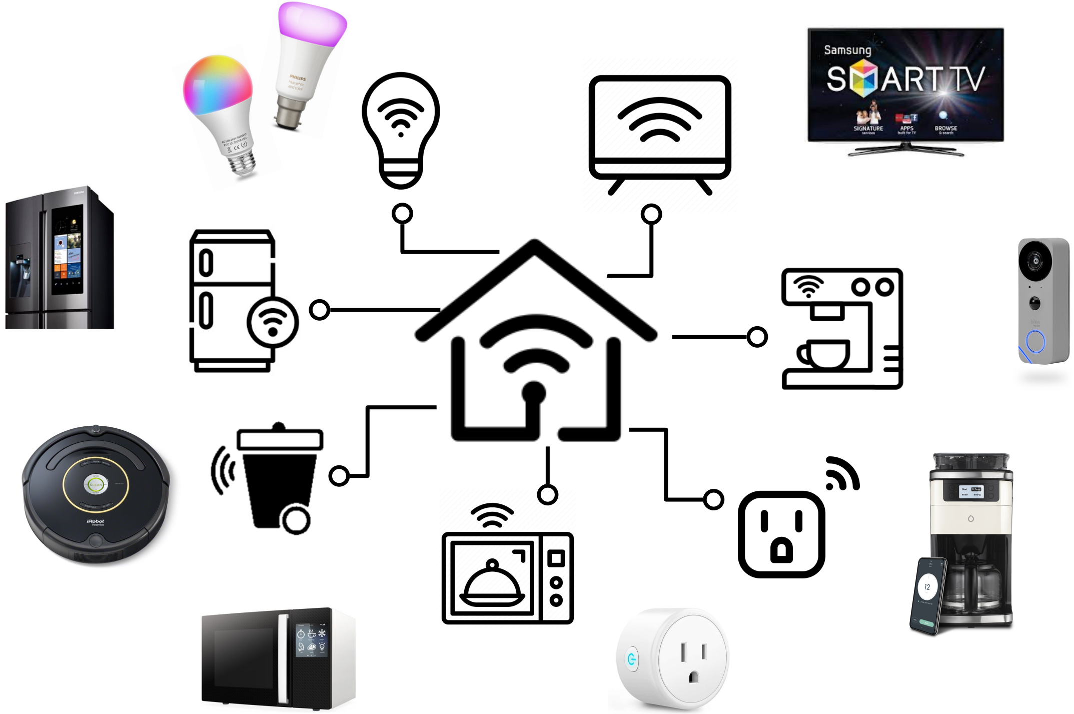
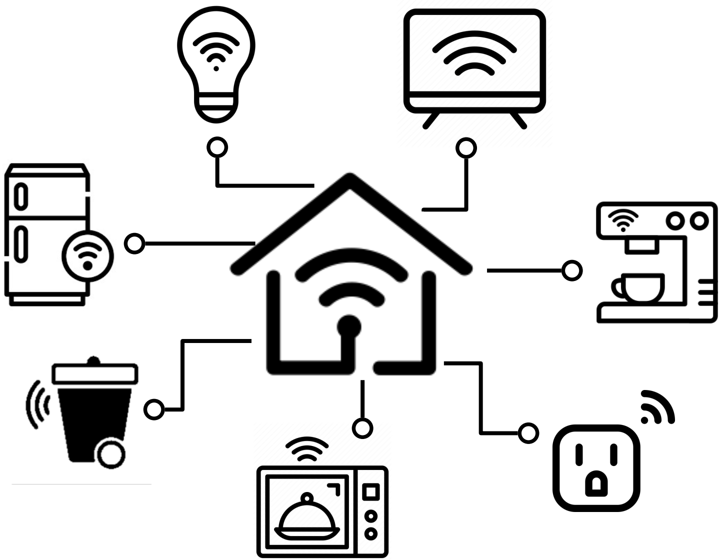
Smart Home World



Smart Home World

Smart Device: 1) connected to other devices via wireless protocols
2) controlled by home automation systems



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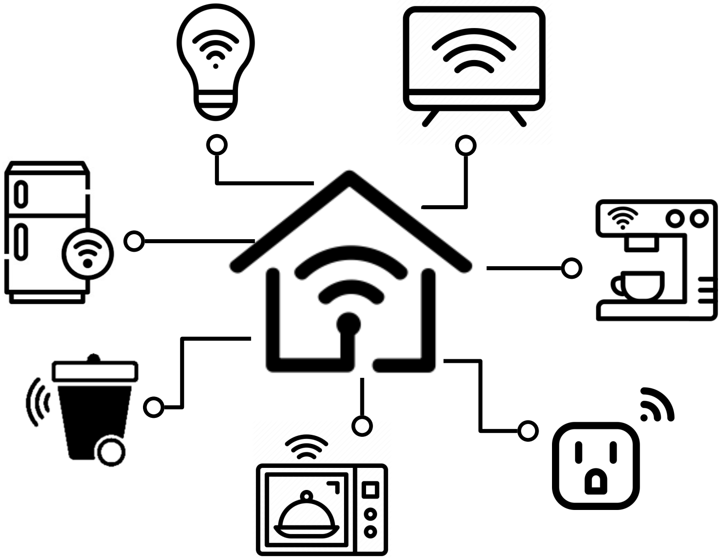


> *"Humans need to control their lives, not control devices."*
>
> -- Davidoff et al, UbiComp'06

Smart Home World (Cont.)

How people control smart home?

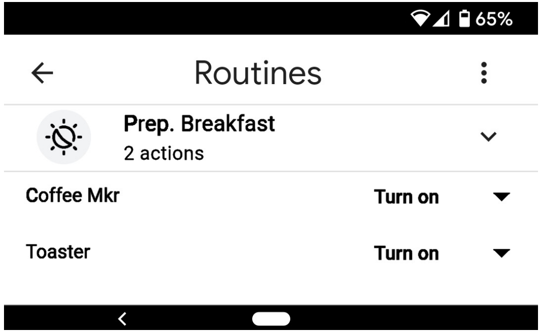
- by *Command*

  e.g. {Make an espresso}

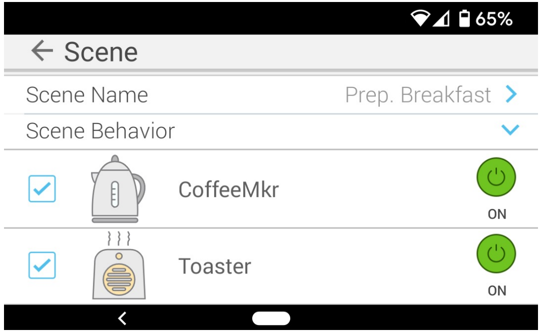
- by *Routine*: *a sequence of commands*

  e.g. Prep. Breakfast = {Make an espresso; make a pancake}

Current systems execute Best-Effort!



Routine in Google Home



Routine in Kasa (TP-Link)

Two Natural Expectations from Users

- Execute everything in a routine – *Atomicity*
    - All commands in the routine need to finish successfully, or none do

- When conflicts happen, people hope routines to execute one after another – *Isolation / Serial Equivalence*

Poorly supported in current systems!

**Routines are common to be long running,* *e.g. trash-out routine.*

SafeHome

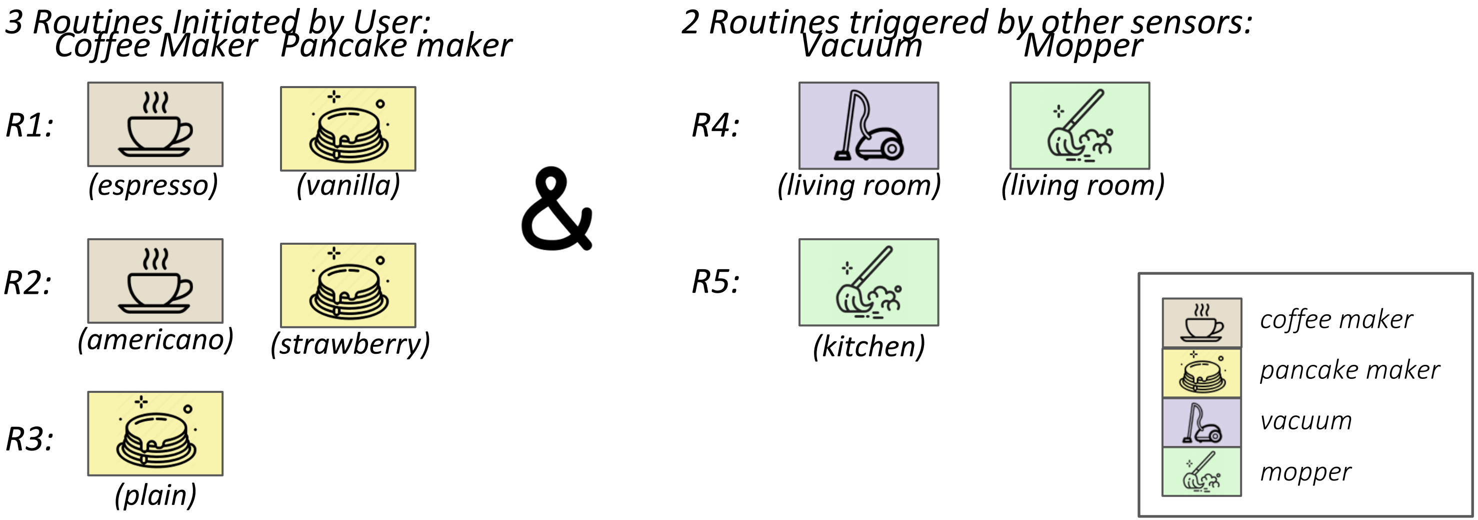
- Home Automation System that can
  - Support *long running* routines
  - Properly *isolate* concurrent routines (providing *serial equivalence*)
  - Ensure routine execution *atomicity*
- Key challenge: Actions are visible to users
- Methodology:
  - Four *Visibility Models* (Spectrum for user choices)
  - *Lock-based* mechanism with *leasing* design

Visibility Models

Four Visibility Models:

- *Weak, Eventual, Partitioned Strict, Global Strict*

Example Scenarios: 5 routines are initiated *simultaneously* on 4 devices

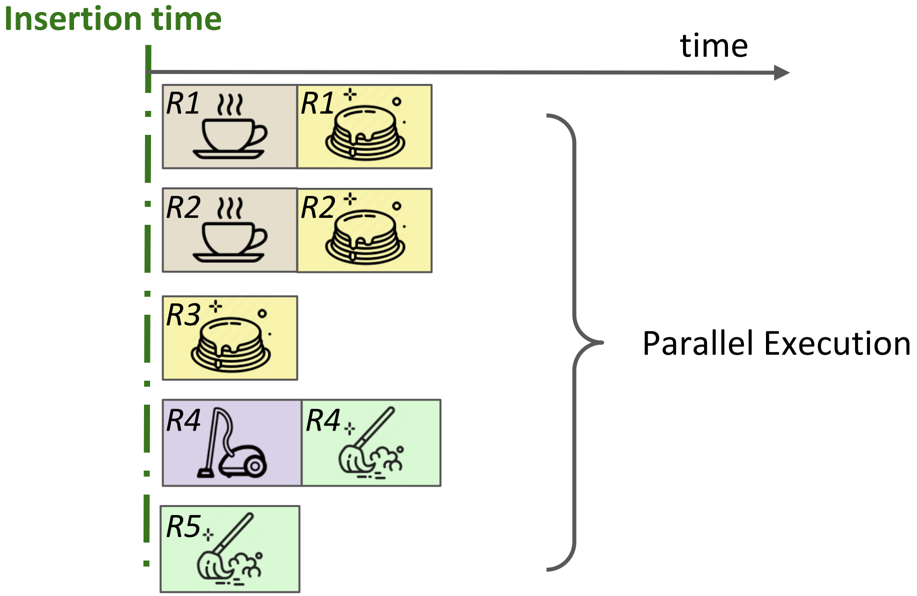


Weak Visibility (WV) Model -- Status Quo

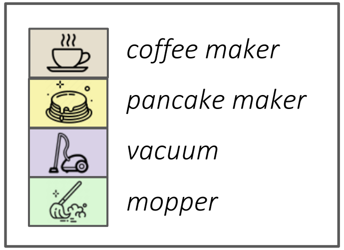
Strategy:

- Execute routine immediately when triggered

Finish in 2 time units



Two commands send simultaneously to one device may cause errors.

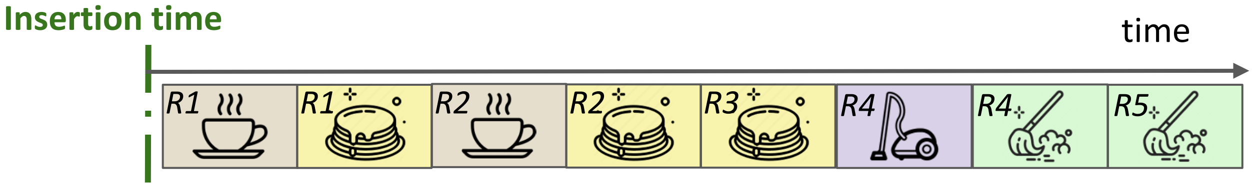


Global Strict Visibility (GSV) Model

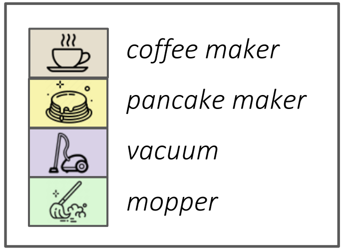
Finish in 8 time units

Strategy:

- Execute at most one routine at a time



- Strongest Visibility Model
- Example Usage: resource constrained environment:
  - e.g. 1000-watt max supply < coffee maker 600W + pancake maker: 600W

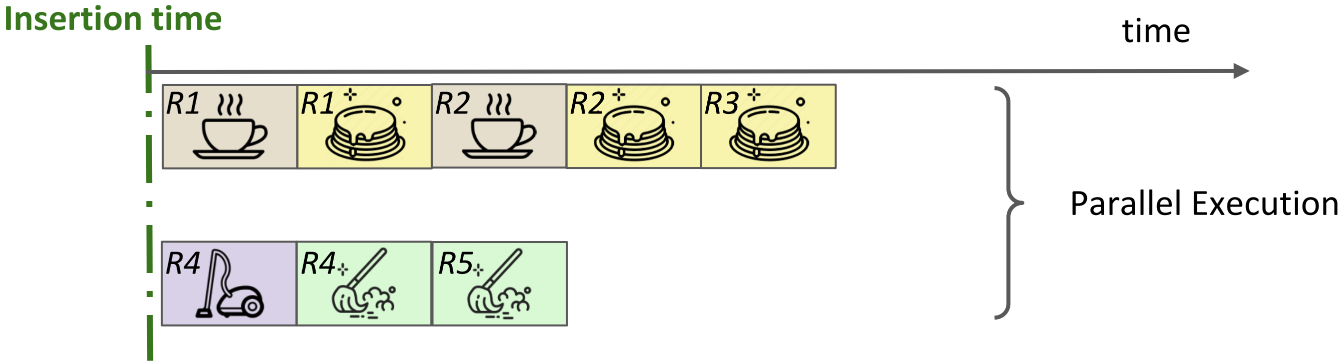


Partitioned Strict Visibility (PSV) Model

Finish in 5 time units

Strategy:

- Routines touching disjoint devices do not block each other



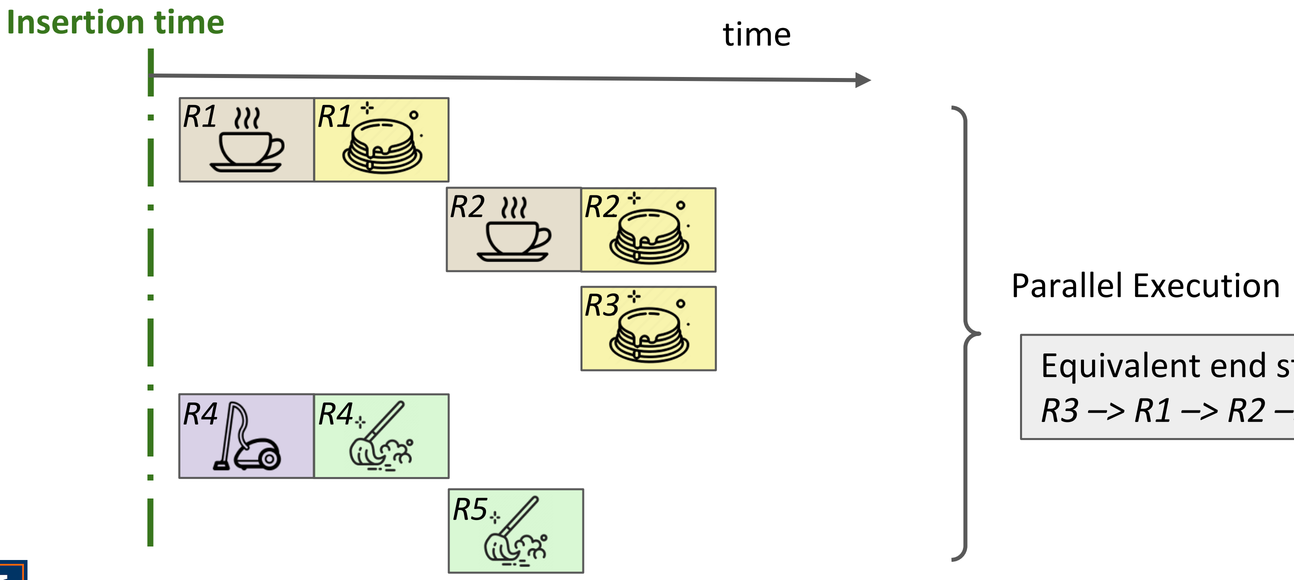
- Useful when routines need to execute without interference through duration.
- Might still takes long with long running routines.

Eventual Visibility (EV) Model

Finish in 3 time units

Strategy:

- Routines can concurrently execute *without violating some serial order*.

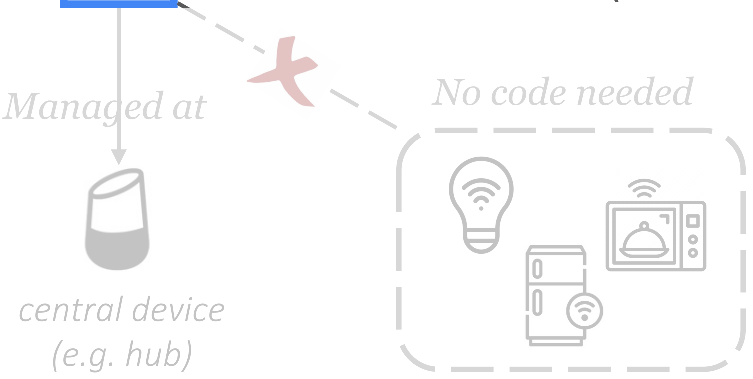


Equivalent end state to:
R3 –> R1 –> R2 –> R5 –> R4

Eventual Visibility (EV) Model

Strategy:

- Routines can concurrently execute *without violating some serial order*.
- Each routine holds the *locks* for devices it touches (but can lease the lock).



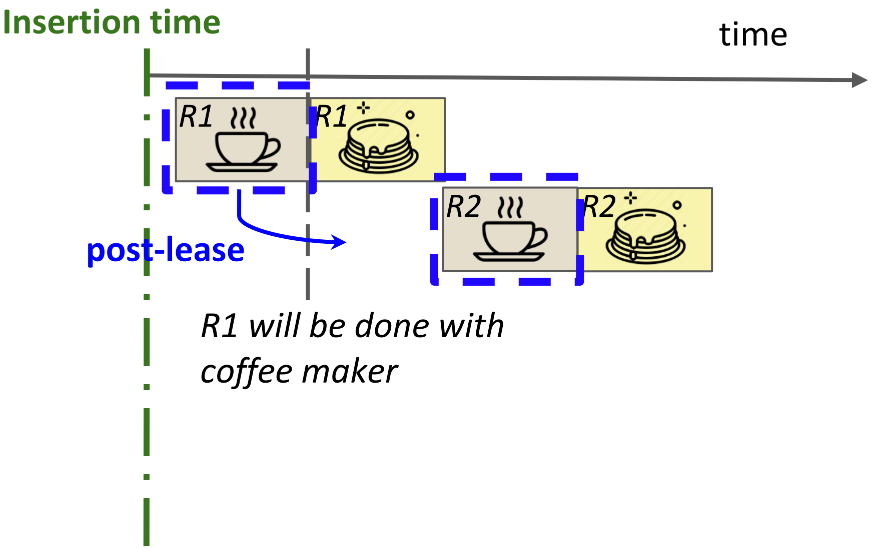
Post-lease

Pre-lease

Eventual Visibility (EV) - Post-Lease

Post-lease:

- If a routine is done with a device *D*, it can post-lease *D*'s lock to another routine.

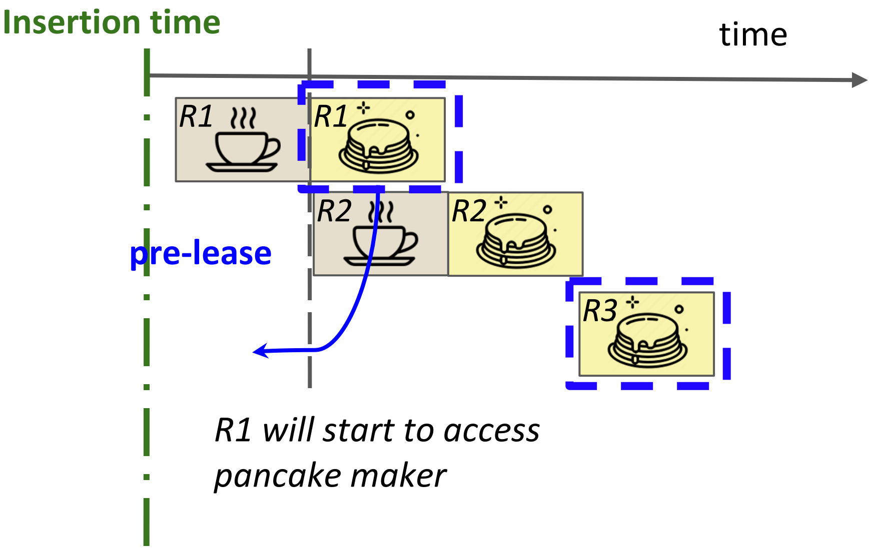


Serial order:
lessor –> lessee
(*R1* –> *R2*)

Eventual Visibility (EV) - Pre-Lease

Pre-lease:

- If a routine has acquired the lock but not accessed a device *D*, it can pre-lease *D*'s lock to another routine.



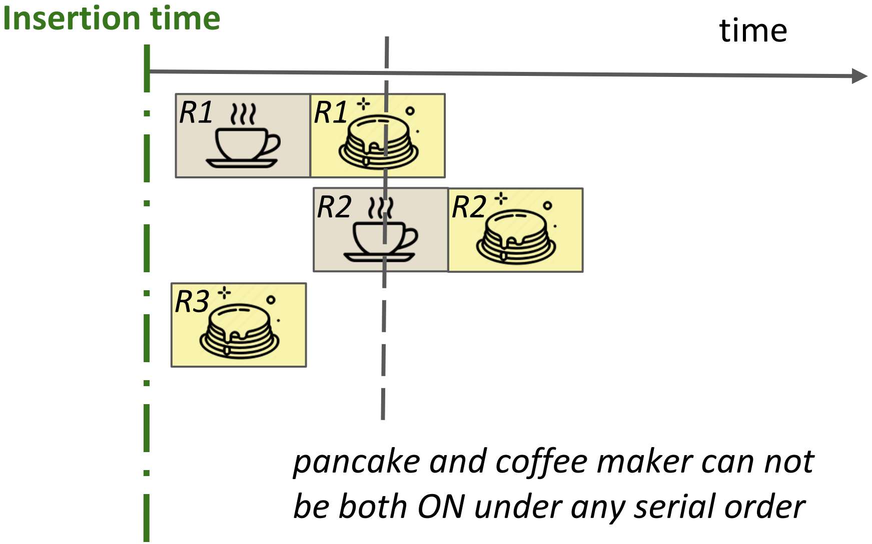
Serial order:
lessee –> lessor
(*R3* –> *R1*)

Eventual Visibility (EV)

EV finishes routine

- with *short wait* and provides *serial equivalence*
- with higher *temporary incongruence: intermediate state is not serially equivalent*

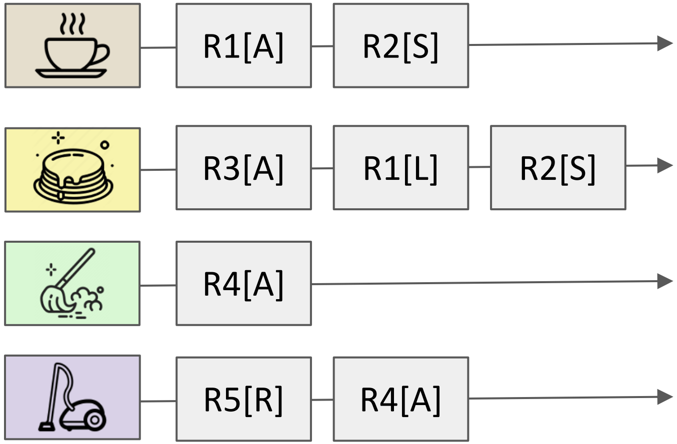
Finish in 3 time units



pancake and coffee maker can not be both ON under any serial order

Eventual Visibility (EV) - Lineage Table

Lineage Table: SafeHome's plan of which routine will access which device.



[A]*: Get lock Access*
[S]*: Routine Scheduled*
[L]*: Lock Leased out*
[R]*: Lock Released*

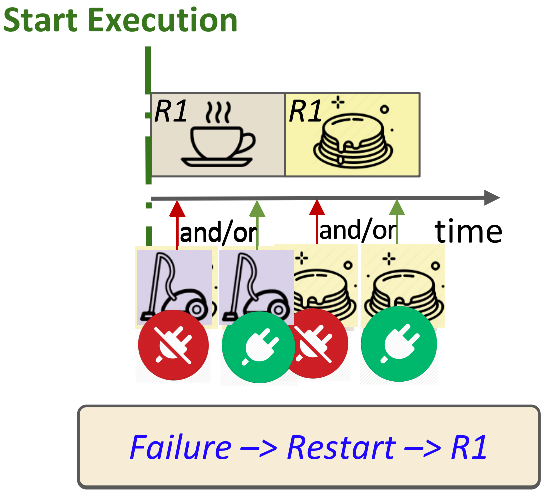
Scheduling plan placement:

- Placed when routine is triggered
- Use *backtracking* for valid placement
- Explore two other policies (FCFS, JiT)

Failure Serialization and Rollback

Device might *fail*:

- *Rollback*? Try to *serialize* the failure/restart event!
- If the failed device is not touched by the routine:
  - *Arbitrary* Serial Equivalence order
- If device fails/restarts after the last touch:
  - *Routine –> Fail/Restart* Serial Equivalence order
- If device fails/restarts before the first touch:
  - *Fail/Restart –> Routine* Serial Equivalence order
- If device fails/restarts during the touch:
  - *Rollback* routine



SafeHome Implementation

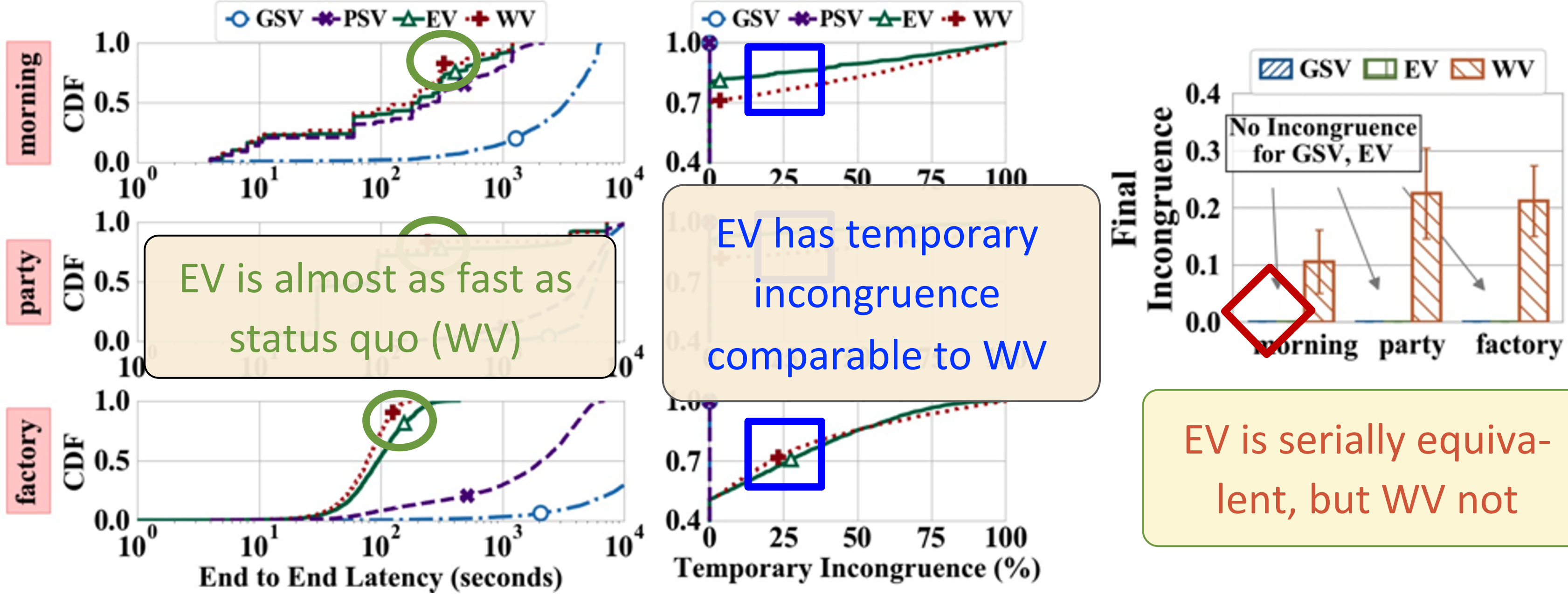
Implementation

- ~2k line of *Java* code
- Support *long running routine* expression (JSON)
- Popular Smart Device *integration* (TP-link, Wemo)

Experiment Setup

- Deployment & Simulation
- Real-world Benchmark
    - Derived from *IoTBench Test Suite*
    - *Morning, Party, Factory* Scenario
- Workload-Driven
    - Average of *500k* runs

Real-World Benchmark



EV is almost as fast as status quo (WV)

EV has temporary incongruence comparable to WV

EV is serially equivalent, but WV not

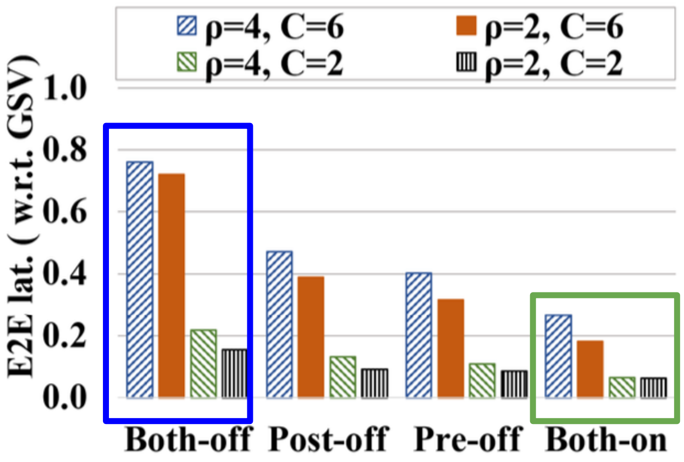
Temporary Incongruence: the ratio of time when ***intermediate*** *state is not serially equivalent.*

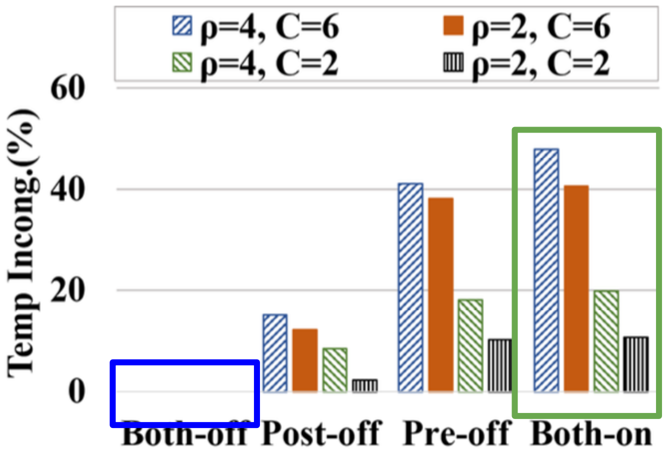
Final Incongruence: the ratio of runs that ***end up*** *in an incongruent state.*

Workload Evaluation -- Pre/Post-Lease

High Latency, Zero Temporary Incongruence

Low Latency, High Temporary Incongruence





Pre/Post leases reduce the E2E latency (user-facing metrics) with the cost of Temporary Incongruence

Takeaways

- Safehome is a first step to provide *reliability* from routine execution level

- SafeHome provides four *Visibility Models* (WV, EV, PSV, and GSV)

- *Eventual Visibility* (EV) model provides the best of both worlds, with:
  - Good user-facing *responsiveness* (0 - 23.1%)
  - Strongest *end state congruence* equivalent guarantee (as GSV)

- Lock-leasing *improves latency* by 1.5X - 4X

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